# Crust Superfluidity

#### Implications for Macroscopic Hydrodynamics



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## Superfluid rotation

Superfluids can be characterised by **macroscopic wave functions**  $\Psi = \Psi_0 e^{i\varphi}$  that satisfy the Schrödinger equation. Using the standard QM formalism one can determine a **superfluid velocity** 

$$\mathbf{v}_{s} \equiv \frac{\mathbf{j}_{s}}{\rho_{s}} = \frac{\hbar}{m_{c}} \nabla \varphi, \qquad \Rightarrow \qquad \boldsymbol{\omega} \equiv \nabla \times \mathbf{v}_{s} = 0.$$
 (1)



Figure 1: Envisage vortices as tiny, rotating tornadoes. Credit: NOAA Photo Library.

- Superflow is irrotational: the superfluids can only rotate by forming a regular vortex array.
- Each vortex carries a **quantum of circulation**  $\kappa = h/2m \approx 2.0 \times 10^{-3} \text{ cm}^2 \text{ s}^{-1}$  and has a size

$$\xi_{\rm v} \approx 1.5 \times 10^{-12} \ \left(1 - x_{\rm p}\right)^{1/3} \ \left(\frac{m}{m_{\rm n}^*}\right) \ \rho_{14}^{1/3} \ \left(\frac{10^{10} \,\rm K}{T_{\rm cn}}\right) \,\rm cm.$$
(2)

## Quantised vorticity

The vortices arrange themselves in a hexagonal array (Abrikosov, 1957) and their circulation mimics solid-body rotation on large scales. The averaged vorticity and vortex area density are given by

$$\boldsymbol{\omega} = 2\boldsymbol{\Omega} = \mathcal{N}_{\mathrm{v}}\kappa\hat{\boldsymbol{z}},$$



Figure 2: Vortex array of a rotating superfluid mimics solid-body rotation.

$$\mathcal{N}_{\rm v} \approx 6.3 \times 10^5 \, \left( \frac{10 \, {\rm ms}}{P} \right) {\rm cm}^{-2}.$$
 (3)

■ For a regular array, the intervortex distance is given by d<sub>v</sub> ≃ N<sub>v</sub><sup>-1/2</sup>:

$$d_{\rm v} \approx 1.3 \times 10^{-3} \left(\frac{P}{10 \, {\rm ms}}\right)^{1/2} \, {\rm cm.}$$
 (4)

A change in angular momentum is achieved by creating (spin-up) or destroying (spin-down) vortices.

## **Mutual friction**

- The vortices interact with the viscous fluid component causing dissipation. This mutual friction influences laboratory systems (Hall and Vinen, 1956) and neutron stars (Alpar et al., 1984b).
- **T**aking  $\Omega = \Omega \hat{\Omega}$ , the **vortex-averaged** drag force in the core is

$$\boldsymbol{F}_{\rm mf} = 2\mathcal{B}\rho_{\rm n}\,\hat{\boldsymbol{\Omega}} \times [\boldsymbol{\Omega} \times (\boldsymbol{\nu}_{\rm n} - \boldsymbol{\nu}_{\rm e})] + 2\mathcal{B}'\rho_{\rm n}\,\boldsymbol{\Omega} \times (\boldsymbol{\nu}_{\rm n} - \boldsymbol{\nu}_{\rm e})\,. \tag{5}$$

■ The dimensionless parameters *B* and *B*' reflect the strength of *F*<sub>mf</sub>. They are calculated by considering mesoscopic **coupling physics** for a single vortex and then averaging for the full array:

$$\mathcal{B} \equiv \frac{\mathcal{R}}{1 + \mathcal{R}^2}, \qquad \qquad \mathcal{B}' \equiv \frac{\mathcal{R}^2}{1 + \mathcal{R}^2}. \tag{6}$$

## **Coupling mechanisms**

- Different processes affect **vortex dynamics** in the crust and the core:
  - phonon excitations (Jones, 1990)
  - Kelvin wave excitations (Epstein and Baym, 1992; Jones, 1992)
  - electron quasi-particle scattering (Feibelman, 1971)
- scattering of electrons off the vortex magnetic field (Alpar et al., 1984b; Andersson et al., 2006)
- Kelvin wave excitations (Link, 2003)



Figure 3: Mutual friction coefficients in the inner crust (left) and the core (right).

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Figure 3: Mutual friction coefficients in the inner crust (left) and the core (right).

### **Basics**

■ Glitches are sudden spin-ups caused by **angular momentum transfer** from a crustal superfluid, decoupled from the lattice (and everything tightly coupled) due to vortex pinning (Anderson and Itoh, 1975).



Figure 4: Sketch of an idealised glitch.

- Catastrophic vortex unpinning triggers the glitch and frictional forces acting on free vortices govern the neutron star's post-glitch response.
- Models of long-term behaviour have been compared to observed exponential relaxation timescales to analyse crustal pinning forces and temperatures (Alpar et al., 1984a, e.g.).
- Observations suggest that the crust spin-up after a glitch is very fast (Dodson et al., 2007; Palfreyman et al., 2018; Ashton et al., 2019 submitted).

- In hydrodynamical models, fast recoupling is captured by Kelvin wave mutual friction ⇒ study glitch rise to analyse corresponding physics.
- Reanalyse Epstein and Baym (1992) and Jones (1992) to understand discrepancies between the two and **determine drag** coefficient *R*:

due to averaging the microscopic pinning interaction over a mesoscopic vortex length scale (Seveso et al., 2016).

Calculate  $\mathcal{B}_{crust} \simeq \mathcal{R}$  for realistic crust model parameters.

#### **Density-dependence**

■ We use the **crustal composition** of Negele and Vautherin (1973) and pinning **interaction parameters** from Epstein and Baym (1992) and Donati and Pizzochero (2006) to calculate B<sub>crust</sub>. Note that the **bottom** of the crust carries the majority of the crustal mass.



Figure 5: Mutual friction strength for kelvin wave coupling as a function of (left) density and (right) relative overlying mass fraction.

#### Three-component model

- Decompose the neutron star into crust superfluid, core superfluid and a non-superfluid 'crust' component. The latter two rotate rigidly and are coupled via a constant mutual friction coefficient B<sub>core</sub> ≈ 5 × 10<sup>-5</sup>.
- Neglecting entrainment for simplicity, the equations of motion are

$$\dot{\Omega}_{\rm sf} = \mathcal{B}_{\rm crust} \left[ 2\Omega_{\rm sf} + \tilde{r} \, \frac{\partial \Omega_{\rm sf}}{\partial \tilde{r}} \right] (\Omega_{\rm crust} - \Omega_{\rm sf}), \tag{8}$$

$$\dot{\Omega}_{\rm core} = \mathcal{B}_{\rm core} 2\Omega_{\rm core} \left(\Omega_{\rm crust} - \Omega_{\rm core}\right), \tag{9}$$

$$\dot{\Omega}_{\rm crust} = -\frac{N_{\rm ext}}{I_{\rm crust}} - \frac{I_{\rm core}}{I_{\rm crust}} \dot{\Omega}_{\rm core} - \frac{1}{I_{\rm crust}} \int \rho \tilde{r}^2 \dot{\Omega}_{\rm sf} \, \mathrm{d}V. \tag{10}$$

■ Relate  $\rho$  and  $\tilde{r}$  in the crust by solving the **TOV equations** for a realistic EoS to obtain  $\mathcal{B}_{crust}(\tilde{r})$  and integrate (8)-(10) in cylindrical geometry for **Vela pulsar** parameters ( $\Omega_{crust}(0) \approx 70 \,\mathrm{Hz}$ ,  $\Delta\Omega_{crit} \approx 10^{-2} \,\mathrm{Hz}$ ) for 120 s.

#### **Differential rotation**

The superfluid rotates **differentially** due to the  $\mathcal{B}_{crust}(\tilde{r})$ -dependence. In the outer layers,  $\mathcal{B}_{crust}$  is strongest and the superfluid couples first. Eventually, the superfluid has transferred all excess angular momentum and spun down to a **new steady state**, where all components corotate.



Figure 6:  $\Omega_{sf}$  as function of radius and time calculated for drag profile (A).

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- We compare different friction profiles by computing the change in crust frequency Δν. The glitch rise shape depends crucially on the relative strength of the crust and core mutual friction.
- With B<sub>core</sub> ~ 5 × 10<sup>-5</sup>, the crust coupling is faster than core coupling, creating a characteristic **overshoot** feature. The onset of crust-core coupling is visible as a break in the **phase shift** φ.



Figure 7: Change in crustal frequency  $\Delta \nu(t) = [\Omega_{crust}(t) - \Omega_{crust}(0)]/2\pi$  and phase shift  $\phi = \int \Delta \nu \, dt$ .

- First single-pulse observations of a glitch in the Vela pulsar (Palfreyman et al., 2018) allow a **comparison** between the data and our predictions.
- Model **timing residuals**  $\Delta t \simeq -2\pi\phi/\Omega_{crust}(0)$  are compared to observed residuals. We include a shift  $\Delta t_0 \approx 0.22 \,\mathrm{ms}$  at the time of the glitch.



Figure 8: Comparison between theoretical (left) timing residuals and (right) cumulative residuals.

Shape is insensitive to crustal profiles as long as  $B_{crust} \gtrsim 10^{-3}$ .

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## Preliminary comparison II

Analyse how sensitive the glitch rise is to  $\mathcal{B}_{core}$  for crustal profile (A):



Figure 9: Comparison between the 2016 Vela glitch data and theoretical predictions calculated for drag profile (A) and a varying crust-core mutual friction strength  $\mathcal{B}_{core}$ .

The data suggests a narrow range  $3 \times 10^{-5} \leq B_{\text{core}} \leq 10^{-4}$ .

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## Improved comparison I

- Use a **Bayesian framework** to fit phenomenological models of the star's rotation frequency to the Vela pulsar data (Ashton et al., 2019 submitted).
- Constrain the **glitch rise time** to less than **12.6** s with 90% confidence.





## Improved comparison II

- We find definite evidence for an **overshoot** and fast decay timescale  $\sim 55 \text{ s} \Rightarrow$  requires three components in a body-averaged formalism.
- We find evidence for a **slow-down** of the star's rotation immediately prior to the glitch ⇒ some **noise** process may trigger the glitch by causing a **critical lag** between crustal superfluid and the lattice.



Figure 11: Frequency evolution during the 2016 Vela glitch: constant frequency model fitted with 200 s-long sliding window with 90% confidence interval (grey) plus maximum-likelihood fits for the overshoot (blue) and slow-down+overshoot (red) models. Dashed curves show the raw frequency evolution, while the solid ones show the time-averaged frequency evolution.

## Conclusions

- Combine realistic crustal **Kelvin-wave profiles** with a simple treatment of the core mutual friction and implement both in a **three-component** neutron star framework  $\Rightarrow$  predictive model suggests that glitch shape depends crucially on the **relative strength** between  $\mathcal{B}_{crust}$  and  $\mathcal{B}_{core}$ .
- Preliminary comparison between our models and the first pulse-to-pulse glitch observations suggest strong crustal combined with weak core mutual frictional  $\Rightarrow$  i.e.  $\mathcal{B}_{crust} \gtrsim 10^{-3}$  and  $3 \times 10^{-5} \lesssim B_{core} \lesssim 10^{-4}$ .
- Bayesian framework allows us to compare phenomenological models and deduce constraints in a model-agnostic way ⇒ constrain the rise time to < 12.6 s, find evidence for overshoot and pre-glitch slow-down.

How does entrainment / the pasta phase entrainment play into this?

# Thank you.



#### Kelvin waves

- In the absence of forces, a vortex supports **Kelvin waves** with angular frequency  $\omega_k = Tk^2/\rho_s\kappa = \hbar k^2/2\mu(k)$  (Thomson, 1880), with tension T and effective mass  $\mu(k) \simeq -2m_u/\ln k\xi$ .
- Vortex-nucleus **interactions** excite waves with wave numbers  $k \leq k_* \equiv (2\mu\Delta v/\hbar l)^{1/2} \Rightarrow$  determine the power *p* transferred into Kelvin waves and relate it to the **resistive force**,  $f_{res} = p/\Delta v$ .
- Epstein & Baym and Jones make **different assumptions** about *p* and the interaction potential including the typical interaction scale *l*:

$$E_{\rm EB}(s) = \frac{E_{\rm s}}{(1+s^2/R_{\rm N}^2)^4} + \frac{E_{\rm l}}{1+s^2/R_{\rm N}^2}, \qquad E_{\rm J}(s) = E_{\rm p} \exp\left(-\frac{s^2}{2\xi^2}\right), \quad (11)$$

where s is the separation,  $E_s$  ( $E_l$ ) a short-range (long-range) interaction contribution,  $R_N$  the nuclear radius and  $\xi$  the coherence length.



## Drag coefficients

- Drag coefficients depend on the relative **vortex-nucleus velocity**, but  $E_{\rm p}$  and  $\Delta v$  are connected by a mesoscopic force balance,  $\Delta v \simeq f_{\rm pin}/\rho_{\rm s}\kappa \sim E_{\rm p}/la\rho_{\rm s}\kappa$ , for a pinning force  $f_{\rm pin}$  per unit length and lattice spacing *a*.
- Correcting several errors in Epstein and Baym (1992) and accounting for a reduction factor δ due to averaging the microscopic pinning interaction over a mesoscopic vortex length scale (Seveso et al., 2016), we find

with  $E_{\rm p}^2 \simeq E_{\rm s}^2 + E_{\rm l}E_{\rm s} + 0.5E_{\rm l}^2$  in Epstein and Baym's formalism.

### Microscopic input

Table 1: Equilibrium composition for five crustal regions taken from Negele and Vautherin (1973) plus vortex-nucleus interaction parameters from Epstein and Baym (1992) and Donati and Pizzochero (2006).

	I	II		IV	V
$n_{\rm b}  \left[ 10^{-4}  {\rm fm}^{-3} \right]$	8.8	57.7	204.0	475.0	789.0
Ζ	40	50	50	40	32
Ν	280	1050	1750	1460	950
ĩ	0.53	0.45	0.35	0.28	0.16
$n_{\rm s}  \left[ 10^{-4}  {\rm fm}^{-3} \right]$	4.8	47.0	184.0	436.0	737.0
$\rho  \left[ 10^{12}  \mathrm{g  cm^{-3}} \right]$	1.5	9.6	33.9	78.9	131.0
A	115	161	193	183	232
$R_{\rm WS}$ [fm]	44.3	35.7	27.6	19.6	14.4
$n_{\rm l}  \left[ 10^{-6}  {\rm fm}^{-3} \right]$	2.7	5.2	11.3	31.7	80.3
<b>a</b> [fm]	90.0	72.5	56.1	39.8	29.2
$R_{\rm N}$ [fm]	5.9	6.7	7.2	7.3	7.2
$E_{\rm s}$ [MeV]	0.42	-0.13	-1.64	-1.00	-0.78
$E_{\rm l}  [{ m MeV}]$	0.16	0.94	1.40	1.00	0.49
$\Delta  [\text{MeV}]$	0.21	0.68	0.91	0.56	0.19
$\xi$ [fm]	15.6	10.1	12.0	26.1	90.8
$E_{\rm p} \; [{ m MeV}]$	0.21	0.29	-2.74	-0.72	-0.02

### Strong core coupling

■ With  $\mathcal{B}_{core} \sim 10^{-2}$  (due to Kelvin wave dissipation), the crustal coupling is slower than core coupling, causing the glitch rise to be **monotonic in time**. The onset of crust-core coupling is not visible in the **phase shift**  $\phi$ .



Figure 12: Change in crustal frequency  $\Delta \nu(t) = [\Omega_{crust}(t) - \Omega_{crust}(0)]/2\pi$  and phase shift  $\phi = \int \Delta \nu \, dt$ .

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