Master UAB - High Energy Physics, Astrophysics and Cosmology

#### NSs, **BHs** and GWs

### **EINSTEIN'S THEORY OF GRAVITY**

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#### <u>Recap I:</u>

#### **Covered last lecture: special relativity**

- Einstein combined earlier results to develop a **new theory of (special) relativity** based on two postulates: i) all inertial frames are equivalent, ii) the speed of light is constant.
- In SR, the laws of physics are invariant under **Lorentz transformations**, which couples space & time into **spacetime**.
- Special relativity **extends Newtonian physics** to those cases where speeds are close to that of light (but gravity negligible).

#### <u>Recap II:</u>

#### **Covered last lecture: tensor calculus**

- To simplify the SR formalism and eventually appreciate the beauty of GR, we make use of **tensor calculus**. We will use tensors to write equations in **coordinate independent** form.
- Tensors are objects satisfying certain properties under **coordinate transformations**. We distinguish scalars (mass), contravariant (tangent vector) and covariant (gradient) tensors.
- Using the formalism, we can encode information about a manifold's **curvature** and determine **geodesics** and **distances**.

#### **Overview:**

**Covered so far: special relativity, tensor calculus** 

Equivalence principles
 Einstein equations
 Why gravity is not a force!
 Schwarzschild solution

#### **Overview:**

**Covered so far: special relativity, tensor calculus** 

Equivalence principles (EPs)
 Einstein equations
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## 1.1 <u>EPs - Mass in Newtonian theory</u>

- So far, we haven't specified what the **mass** of a body actually is. In principle, one can distinguish 3 different masses:
  - **inertial mass m<sup>i</sup>:** measure of a body's resistance to a change in motion; mass in Newton's second law  $\mathbf{F} = m^{i}\mathbf{a}$ .
  - **passive gravitational mass m<sup>p</sup>:** measure of a body's response to a gravitational field,  $\mathbf{F} = -\mathbf{m}^{p}$  grad  $\phi$ .
  - **active gravitational mass m<sup>a</sup>:** measure of a body's strength to produce a gravitational field,  $\phi = -Gm^a/r$ .
- **Galileo** already realised in ~1610 that two bodies (of different mass) dropped from some height **reach** the ground **together**.

# 1.2 Galileo's or the weak EP (WEP)

• Galileo's observation suggests: *all* particles (regardless of mass and composition) fall with the same acceleration when placed in the same gravitational field. This is **one form** of the WEP. It implies that **free fall is universal**.



• This principle combined with Newton's laws suggests further that the **two gravitational masses** are **identica**l and also **equivalent** to the **inertial mass**, i.e., m = m<sup>i</sup> = m<sup>p</sup> = m<sup>a</sup>.

# 1.3 EPs - Mass equivalence

• Equivalence of inertial and gravitational mass is one of the most **accurately tested principles** in physics. Experiments typically measure the **Eötvös parameter** for two test masses A and B:  $\eta(A, B) = 2 \frac{\left(\frac{m^g}{m^i}\right)_A - \left(\frac{m^g}{m^i}\right)_B}{\left(\frac{m^g}{m^i}\right)_A + \left(\frac{m^g}{m^i}\right)_B}$ 



 The best constraint comes from the MICROSCOPE experiment onboard a satellite, confirming the universality of free fall with a **precision of 10<sup>-15</sup>**, a factor 100 better than tests on Earth.

# 1.4 EPs - Einstein's contribution

- Einstein realised that no body can be shielded from a gravitational field, but we can **locally remove effects of gravity** (& recover SR) by considering a **free falling reference frame**.
- Someone falling from a roof feels weightless, so locally there is no gravitational field and we have an inertial frame. Free falling observers are inertial observer!
- A frame **linearly accelerating** in empty space is locally identical to a **frame at rest** in a gravitational field.



# 1.5 <u>Einstein's EP</u>

- We cannot distinguish between gravitational & inertial forces (accelerations) with any local experiment using test particles:
  - Gravitational forces can be described like inertial forces!



- When gravitational accelerations are present, then space cannot be flat: a **gravitational field curves spacetime**!
- If gravity is present, **no inertial frames** can exist: there are no special frames & we have to use general coordinates!

# 1.6 The strong EP (SEP)

- The WEP is only applicable to **test particles** and local but **non-gravitational experiments**. A stronger statement is: *The WEP also holds for self-gravitating bodies (like stars) and any type of experiment (gravitational or non-gravitational).*
- This form is **more restrictive** than the WEP: **only GR** seems to satisfy the SEP. Other gravity theories violate it to some level.
- SEP tests involve searching for variations in G or compact binaries (with at least one pulsar to 'measure' effects) as they strongly affect the spacetime.



# 1.7 EPs - Locality vs. non-locality

• Local experiments not only imply that an observer cannot look outside of their laboratory / spacecraft, but also that the lab / spacecraft is small enough so that tidal effects (due to a gradient in the gravitational field) are not detected.



If their **rocket** is **wide** enough and the observer's **equipment sensitive** to detect **changes in a gravitational field**, they could distinguish the two cases illustrated on the left.

## 1.8 <u>Questions</u>

- Go to <u>www.menti.com</u> & enter 1217 3573.
  - 1. Does the universality of free fall imply that m<sup>i</sup> = m<sup>g</sup>?
     Yes
     No
  - 2. A (non-rotating) observer is able to perform a local experiment to determine whether they are freely falling in a gravitational field or moving at v=const in empty space.
     Correct
    - Incorrect

## 1.8 Answers

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#### **Overview:**

Covered so far: special relativity, tensor calculus, equivalence principles

Equivalence principles
 Einstein equations (EEs)
 Why gravity is not a force!
 Schwarzschild solution

## 2.1 EEs - Minkowski spacetime

- As we have seen now, the **flat spacetime** we encountered in the Special Theory of Relativity plays an important role when gravity is absent or local inertial observers are considered.
- We can now write the **line element** in tensorial form using the **Minkowski metric**  $g_{ab} = \eta_{ab}$ :  $ds^2 = \eta_{ab} dx^a dx^b$

$$\eta = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$

Considering the length (norm) X<sup>2</sup> = X<sub>a</sub>X<sup>a</sup> of a vector, we distinguish timelike (X<sup>2</sup>>0), spacelike (X<sup>2</sup><0) or lightlike / null (X<sup>2</sup>=0) vectors.

#### 2.2 <u>EEs - Exercise</u>

- Let's define a timelike geodesic as a geodesic, whose tangent vector is timelike everywhere. Show that the so-called proper time τ (time measured by a clock following this geodesic, with dτ = ds/c) between t<sub>1</sub> and t<sub>2</sub> is given by
  - The following relations will help:

$$\tau = \int_{t_1}^{t_2} \frac{\mathrm{d}t}{\gamma(t)}$$

$$ds^{2} = c^{2}dt^{2} - dx^{2} - dy^{2} - dz^{2}$$
$$\gamma = 1/\sqrt{1 - v^{2}/c^{2}} \qquad \mathbf{v} = \left(\frac{dx}{dt}, \frac{dy}{dt}, \frac{dz}{dt}\right)$$

## 2.2 <u>EEs - Exercise</u>

#### • Solution:

$$\begin{aligned} \tau &= \int_{t_1}^{t_2} \mathrm{d}\tau = \int_{t_1}^{t_2} \frac{\mathrm{d}s}{c} = \int_{t_1}^{t_2} \frac{1}{c} \sqrt{c^2 \mathrm{d}t^2 - \mathrm{d}x^2 - \mathrm{d}y^2 - \mathrm{d}z^2} \\ &= \int_{t_1}^{t_2} \mathrm{d}t \sqrt{1 - \frac{1}{c^2} \left[ \left(\frac{\mathrm{d}x}{\mathrm{d}t}\right)^2 + \left(\frac{\mathrm{d}y}{\mathrm{d}t}\right)^2 + \left(\frac{\mathrm{d}z}{\mathrm{d}t}\right)^2 \right]} \\ &= \int_{t_1}^{t_2} \mathrm{d}t \sqrt{1 - \frac{v(t)^2}{c^2}} = \int_{t_1}^{t_2} \frac{\mathrm{d}t}{\gamma(t)} \end{aligned}$$

# 2.3 EEs - The ideas

- All our considerations helped Einstein develop a **range of arguments** that determine how the equations that completely control the **dynamics of gravitation** will have to look like:
  - The *correct Newtonian limit* has to be recovered.
  - The equations should have *tensorial form*.
  - Mass and energy are sources of the gravitational field, so the *energy-momentum tensor*  $T_{ab}$  should appear.
  - Energy-momentum has to be *conserved*.
  - Second derivatives of the metric combined into some order 2 tensor  $A_{ab}$  should enter the equations.

# 2.4 Einstein equations

• Combining these suggests the following:

$$G_{ab} = R_{ab} - \frac{1}{2}Rg_{ab} = \kappa T_{ab} = \frac{8\pi G}{c^4}T_{ab}$$

 $\nabla_a T^{ab}$ 

• In **vacuum (empty space)**, these reduce to the simple case

$$T_{ab} = 0, \quad R_{ab} = 0$$

#### 2.5 <u>EEs - Energy-momentum tensor</u>

- A generalisation of the Newtonian stress tensor, T<sub>ab</sub> describes the density and flux of energy and momentum in spacetime.
- In GR, the tensor is **symmetric** T<sub>ab</sub> = T<sub>ba</sub> and its **precise form** depends on the **type of matter/energy** considered, e.g.,
  - Non-interacting matter (dust):

$$T^{ab} = \rho_0 u^a u^b$$

 $u^a = \frac{\mathrm{d}x^a}{\mathrm{d}\tau}$ 

- Perfect fluid:  $T^{ab} = (\rho_0 + p/c^2)u^a u^b pg^{ab}$
- From the **conservation law**  $\nabla_a T^{ab} = 0$  we recover conservation equations, e.g., continuity / Navier-Stokes / Maxwell equations.

### 2.6 <u>EEs - Geodesics part II</u>

 We saw that a free particle (no external forces acting) follows a geodesic. These curves are typically parameterised by the proper time, i.e., u = τ. Thus, for a timelike geodesic:

$$\frac{\mathrm{d}^2 x^a}{\mathrm{d}^2 \tau} + \Gamma^a{}_{bc} \frac{\mathrm{d} x^b}{\mathrm{d} \tau} \frac{\mathrm{d} x^c}{\mathrm{d} \tau} = 0$$

τ is an affine parameter (the tangent vector remains parallel or equivalently the acceleration is perpendicular to the curve / velocity vector). Note that the coordinate time t is not an affine parameter and the equation of motion would differ.

## 2.7 <u>EEs - Newtonian limit I</u>

• If our **spacetime is almost flat**, we expect the metric to differ only slightly from the Minkowski metric, i.e.,

$$g_{ab} = \eta_{ab} + \epsilon h_{ab} + \mathcal{O}(\epsilon^2) \quad \text{with} \quad \epsilon \sim v/c \ll 1$$

In the slow-motion limit, we can also assume that differentials w.r.t x<sup>o</sup> = ct are larger than the spatial ones w.r.t. x<sup>α</sup> = (x,y,z):



From c dτ = ds, we find to lowest order in ε that τ~t, while the definition of the **connections** suggest that

 Γ<sup>a</sup><sub>bc</sub> = O(ε)

## 2.8 <u>EEs - Newtonian limit II</u>

• We are now interested in the **geodesic equation**, specifically the spatial components. To first order in ε, we find

$$\begin{split} 0 &= \frac{1}{c^2} \frac{\mathrm{d}^2 x^{\alpha}}{\mathrm{d}^2 t} + \frac{1}{c^2} \, \Gamma^{\alpha}{}_{bc} \frac{\mathrm{d} x^b}{\mathrm{d} t} \frac{\mathrm{d} x^c}{\mathrm{d} t} \sim \frac{1}{c^2} \frac{\mathrm{d}^2 x^{\alpha}}{\mathrm{d}^2 t} + \Gamma^{\alpha}{}_{00} \\ &= \frac{1}{c^2} \frac{\mathrm{d}^2 x^{\alpha}}{\mathrm{d}^2 t} - \frac{1}{2} \epsilon \left( 2 \frac{\partial h_{0\alpha}}{\partial x^0} - \frac{\partial h_{00}}{\partial x^{\alpha}} \right) \sim \frac{1}{c^2} \frac{\mathrm{d}^2 x^{\alpha}}{\mathrm{d}^2 t} + \frac{1}{2} \epsilon \frac{\partial h_{00}}{\partial x^{\alpha}} \end{split}$$

• Analogy with the Newtonian equation gives **weak-field limit** 

$$\frac{\mathrm{d}^2 x^{\alpha}}{\mathrm{d}^2 t} = -\frac{\partial \phi}{\partial x^{\alpha}}, \quad \Rightarrow \quad g_{00} = 1 + 2\frac{\phi}{c^2} + \mathcal{O}\left(\frac{v}{c}\right)$$

## 2.9 Questions

- Go to <u>www.menti.com</u> & enter 7508 1331.
  - 1. Which of these statements does not hold for the EEs?
    - Second derivatives of  $g_{ab}$  should appear.
    - The equations have scalar form.
    - Newtonian physics need to be recovered.
  - 2. Free particles move along geodesics. If external forces are present, we can account for these by adding extra force terms  $f^a$  to the rhs of our geodesic equation?
    - Yes
    - No

#### 2.9 Answers

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  - $\circ$  1. Which of these statements does not hold for the EEs?
    - Second derivatives of  $g_{ab}$  should appear.
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  - $\circ$  2. Free particles move along geodesics. If external forces are present, we can account for these by adding extra force terms f<sup>a</sup> to the rhs of our geodesic equation?
    - Yes No

$$\frac{\mathrm{d}^2 x^a}{\mathrm{d}^2 \tau} + \Gamma^a{}_{bc} \frac{\mathrm{d} x^b}{\mathrm{d} \tau} \frac{\mathrm{d} x^c}{\mathrm{d} \tau} = 0$$

#### **Overview:**

Covered so far: special relativity, tensor calculus, equivalence principles, Einstein equations

Equivalence principles
 Einstein equations
 Why gravity is not a force!
 Schwarzschild solution

# 3.1 <u>Video</u>

- To make sure that we have all understood the main concepts discussed in class so far, we are going to watch the following **Youtube video**. It summarises all the elements we have introduced in the last lecture and today (in ~15 min!!):
  - Why Gravity is NOT a Force by Veritasium

https://tinyurl.com/a3ean3tc

• To break things up, we will watch in **two blocks** and have 2 rounds of questions.



## **3.2 <u>Questions</u>** https://tinyurl.com/a3ean3tc

- Watch **until 6:55** & go to <u>www.menti.com</u> & enter 7861 1865.
  - 1. An observer in a spacecraft approaching a planet will not notice any difference but an external observer will see the spacecraft move on a bent path due to spacetime curvature?
     Incorrect
    - Correct
  - 2. Why can the bent sheet or rubber sheet analogy of GR be somewhat misleading? Please type out your answer in 1 or 2 sentences, but not more.

## 3.2 Answers

- Watch **until 6:55** & go to <u>www.menti.com</u> & enter 1874 9092.
  - 1. An observer in a spacecraft approaching a planet will not notice any difference but an external observer will see the spacecraft move on a bent path due to spacetime curvature?
     Incorrect
    - Correct
  - 2. The object's motion around the central mass is closer to the analogy of an object falling into a well due to a gravitational force. But in GR gravity is not a force and the test mass travels on a straight path through curved spacetime.

## **3.3 <u>Questions</u>** https://tinyurl.com/a3ean3tc

- Watch **the rest** & go to <u>www.menti.com</u> & enter 4162 1019.
  - 3. How can you be at rest (on the Earth's surface) if you are a non-inertial observer and 'accelerating upwards'? Please type out your answer in **1 or 2** sentences, but not more.
  - 4. GR predicts that in an accelerating frame of reference & similarly in curved spacetime the paths of light are bent.
    Correct
    - Incorrect

## 3.3 Answers

- Watch the rest & go to <u>www.menti.com</u> & enter 4162 1019.
  - 3. A stationary position is possible if our acceleration is exactly cancelled by the product of a curvature term times the velocity squared. We can mathematically show this by adding force/acceleration terms to our geodesic equation.
  - GR predicts that in an accelerating frame of reference & similarly in curved spacetime the paths of light are bent.
     Correct
    - Incorrect

#### **Overview:**

Covered so far: special relativity, tensor calculus, equivalence principles, Einstein equations

Equivalence principles
 Einstein equations
 Why gravity is not a force!
 Schwarzschild solution (SS)

# 4.1 <u>SS - Solving EEs</u>

- EEs are very **complicated** and difficult to solve, but there are a **few cases** where we can take advantage of special properties of the gravitational system and find **analytical solutions**.
- One such case is the **Schwarzschild solution** for which we will assume that the following statements hold:
  - a.) Spacetime is *spherically symmetry*.
  - b.) Spacetime is *static*.
  - c.) Spacetime is *empty*.
  - d.) Spacetime is *asymptotically flat*.



## 4.2 <u>SS - General solution for a. & b.</u>

- In broad terms, a **static spacetime** is one that does not change over time and is also irrotational. This implies that
  - i.) all *metric components* g<sub>ab</sub> are independent of x<sup>o</sup>.
    ii.) the *line element* ds<sup>2</sup> is invariant under x<sup>o</sup> → x<sup>o</sup>.
- A metric that only satisfies i.) is called stationary. If both hold, ds<sup>2</sup> can only depend on rotational invariants of x<sup>α</sup> and their differentials, which implies the metric is isotropic. The most general spherically symmetric line element is given by

$$ds^{2} = e^{\nu(t,r)} dt^{2} - e^{\lambda(t,r)} dr^{2} - r^{2} (d\theta^{2} + \sin^{2}\theta d\phi^{2})$$

# 4.3 SS - Schwarzschild metric

• What remains is the **determination of** the **two functions** v and  $\lambda$ . To do this, we would have to consider the vacuum Einstein Equations and calculate  $R_{ab} = 0$  for our isotropic metric

$$g_{ab} = \operatorname{diag}(e^{\nu}, -e^{\lambda}, -r^2, -r^2\sin^2\theta)$$

One would find that λ = λ(r) & v = v(r) as well as v(r) = - λ(r), and explicitly for the Schwarzschild line element

$$ds^{2} = (1 - 2m/r)dt^{2} - (1 - 2m/r)^{-1}dr^{2} - r^{2}(d\theta^{2} + \sin^{2}\theta d\phi^{2})$$

## 4.4 <u>SS - Observations</u>

- In the **asymptotic limit** r → ∞, we recover the flat metric in spherical coordinates, i.e., the SS metric is asymptotically flat.
- We can learn more about the quantity m in the line element, by considering the weak-field limit. On slide 2.8, we saw that in this case g<sub>00</sub> ~ 1+2φ /c<sup>2</sup>. For a point mass M at the origin, Newtonian theory gives rise to a potential φ = GM/r. Thus

$$1 + 2\phi/c^2 = 1 - 2GM/c^2r \stackrel{!}{=} 1 - 2m/r \quad \Rightarrow \quad m = GM/c^2$$

• We interpret the SS solution as due to a point particle at the origin, with m as the **(geometric) mass** in relativistic units.

# 4.5 <u>SS - Birkhoff's theorem</u>

- While we have seen that the SS metric is a static & spherically symmetric solution of the vacuum Einstein equations, it is possible to show that this solution is **unique**. This implies that
  - any spherically symmetric solution of the vacuum field equations must be static and asymptotically flat.
  - spacetime outside of a spherical, nonrotating, gravitating body (exterior solution) MUST be given by the SS metric.
- A **spherically pulsating star** has a static exterior and **cannot emit GWs**.



## 4.6 <u>Questions</u>

- Go to <u>www.menti.com</u> & enter 7730 7235.
  - 1. A static solution to the Einstein Equations is always stationary, but the opposite is not automatically true.
     Correct
    - Incorrect
  - 2. We interpret the Schwarzschild solution to the vacuum Einstein Equations as due to a point particle at the origin.
     No
    - Yes

#### 4.6 Answers

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  - 1. A static solution to the Einstein Equations is always stationary, but the opposite is not automatically true.
     Correct
    - Incorrect
  - 2. We interpret the Schwarzschild solution to the vacuum Einstein Equations as due to a point particle at the origin.
    No
    Yes

#### **Summary I:**

**Covered today: equivalence principles, Einstein equations, Schwarzschild solution** 

- The **weak equivalence principle** has multiple forms, reflecting the fact that we cannot distinguish between gravitational & inertial forces with any local experiment using test particles.
- The **strong equivalence principle** generalises the WEP to self-gravitating bodies and gravitational experiments.
- The **Einstein equations** are a set of tensor equations that completely control the **dynamics of gravitation**.

#### <u>Summary II:</u>

**Covered today: equivalence principles, Einstein equations, Schwarzschild solution** 

- The essence of the Einstein equations is that "Spacetime tells matter how to move, while matter tells spacetime how to curve." as summarised by John Wheeler.
- In General Relativity, **gravitational phenomena** arise not from forces or fields but from the curvature of spacetime itself.
- The (unique) **spherically symmetric & static solution** of the vacuum Einstein Equations is **Schwarzschild's solution**.